

Geometric Analogue of Holographic Reduced Representations

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Outline

- Background
 - Distributed representations
 - Previous architectures
- GA model
 - Binary parametrization of the geometric product
 - Cartan representation
 - Example
 - Signatures
- Test results
 - Recognition tests
 - Blade linearity
- Future work
- Computer program *CartanGA*

Distributed representations

Example

Distributed representations

Example



“green color”



+ “triangular shape”



= “green triangle”

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- An opposite and an alternative of “traditional” data structures (lists, databases, etc...).

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 - the units have either binary or a continuous-space values
 - data patterns are chosen as random vectors or matrices
 - in most distributed representations only the overall pattern of activated units has a meaning (resemblance to a multi-superimposed photograph)

Distributed representations

Atomic objects and complex statements

Distributed representations

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$$\underbrace{bite_{agent} \circledast Fido}_{chunk} + \underbrace{bite_{object} \circledast Pat}_{chunk} = \text{"Fido bit Pat"}$$

- roles: $bite_{agent}$, $bite_{object}$
- fillers: $Fido$, Pat

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$$\textit{name} \circledast \textit{Pat} + \textit{sex} \circledast \textit{male} + \textit{age} \circledast 66 = \text{"PSmith"}$$

- roles: *name*, *sex*, *age*
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$$\text{see}_{\text{agent}} \circledast \text{John} + \text{see}_{\text{object}} \circledast \text{"Fido bit Pat"} = \text{"John saw Fido bit Pat"}$$

- Roles are always atomic objects but fillers may be complex statements.

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Binding and chunking

- \circledast binding
- + superposition (also called *chunking*)

Distributed representations

Decoding

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x^{-1} (approximate/pseudo) inverse

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Examples

“What is the name of PSmith?”

- $(name \otimes Pat + sex \otimes male + age \otimes 66) \ddagger name^{-1} = Pat + noise \approx Pat$

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“What did Fido do?”

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Clean-up memory

- An auto-associative collection of elements and statements (excluding single chunks) produced by the system.
- Given a noisy extracted vector such structure must be able to:
 - either recall the most similar item stored ...
 - ... or indicate, that no matching object had been found.
- We need a measure of similarity (in most models: scalar product, Hamming/Euclidean distance).

Distributed representations

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Advantages

- Noise tolerance, good error correction properties.
- Storage efficiency.
- The number of superimposed patterns is not fixed.

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$$\left((bite + bite_{agent} \otimes Fido + bite_{object} \otimes Pat)/\sqrt{3} \right) \otimes bite_{agent}^*$$
- Similarity measure: dot product

Binary parametrization of the geometric product

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Let $\{x_1, \dots, x_n\}$ be a string of bits and $\{e_1, \dots, e_n\}$ be base vectors. Then

$$e_{x_1 \dots x_n} = e_1^{x_1} \dots e_n^{x_n}$$

where $e_k^0 = \mathbf{1}$.

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$$1 = e_{0\dots 0}$$

$$e_1 = e_{10\dots 0}$$

$$e_{235} = e_{011010\dots 0}$$

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$$\begin{aligned} e_{12}e_1 &= e_{110\dots 0}e_{10\dots 0} = e_1e_2e_1 = -e_2e_1e_1 = -e_2 = -e_{010\dots 0} \\ &= -e_{(110\dots 0)\oplus(10\dots 0)} = (-1)^D e_{(110\dots 0)\oplus(10\dots 0)} \end{aligned}$$

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More formally, for two arbitrary strings of bits we have:

$$e_{A_1 \dots A_n} e_{B_1 \dots B_n} = (-1)^{\sum_{k < l} B_k A_l} e_{(A_1 \dots A_n) \oplus (B_1 \dots B_n)}$$

Matrix representation

Pauli's matrices

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

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Cartan representation

$$b_{2k} = \underbrace{\sigma_1 \otimes \cdots \otimes \sigma_1}_{n-k} \otimes \sigma_2 \otimes \underbrace{1 \otimes \cdots \otimes 1}_{k-1},$$
$$b_{2k-1} = \underbrace{\sigma_1 \otimes \cdots \otimes \sigma_1}_{n-k} \otimes \sigma_3 \otimes \underbrace{1 \otimes \cdots \otimes 1}_{k-1}.$$

Example

Representation

*PSmith = name * Pat + sex * male + age * 66*

Example

Representation

$PSmith = name \otimes Pat + sex \otimes male + age \otimes 66$

$Pat = c00100$

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$Pat = c00100 = b_3$

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$$Pat = c_{00100} = b_3 = \sigma_1 \otimes \sigma_1 \otimes \sigma_1 \otimes \sigma_3 \otimes 1$$

$$male = c_{00111} = b_3 b_4 b_5$$

$$= (\sigma_1 \otimes \sigma_1 \otimes \sigma_1 \otimes \sigma_3 \otimes 1)(\sigma_1 \otimes \sigma_1 \otimes \sigma_1 \otimes \sigma_2 \otimes 1)(\sigma_1 \otimes \sigma_1 \otimes \sigma_3 \otimes 1 \otimes 1)$$

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Encoding and Decoding

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$$PSmith's\ name = PSmith \# name^{-1} = PSmith \otimes name$$

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$$PSmith \circledast name = (-c_{00110} + c_{11011} + c_{01001}) c_{00010}$$

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 &= c_{00010} c_{00100} + c_{11100} c_{00111} + c_{10001} c_{11000} \\
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 \end{aligned}$$

$$PSmith's\ name = PSmith \# name^{-1} = PSmith \circledast name$$

$$\begin{aligned}
 PSmith \circledast name &= (-c_{00110} + c_{11011} + c_{01001}) c_{00010} \\
 &= -c_{00100} - c_{11001} - c_{01011}
 \end{aligned}$$

Example

Encoding and Decoding

PSmith

$$\begin{aligned}
 PSmith &= name \circledast Pat + sex \circledast male + age \circledast 66 \\
 &= c_{00010} c_{00100} + c_{11100} c_{00111} + c_{10001} c_{11000} \\
 &= -c_{00110} + c_{11011} + c_{01001}
 \end{aligned}$$

$$PSmith's\ name = PSmith \# name^{-1} = PSmith \circledast name$$

$$\begin{aligned}
 PSmith \circledast name &= (-c_{00110} + c_{11011} + c_{01001}) c_{00010} \\
 &= -c_{00100} - c_{11001} - c_{01011} \\
 &= -Pat + noise = Pat'
 \end{aligned}$$

Example

Clean-up

Scalar product

Scalar (inner) product is performed by the means of matrix trace.

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Scalar (inner) product is performed by the means of matrix trace.

$$\begin{aligned}
 \langle Pat' | e_{Pat} \rangle &= Tr\left((-c_{00100} - c_{11001} - c_{01011})c_{00100}\right) \\
 &= Tr\left(-\mathbf{1} + c_{11101} - c_{01111}\right) \\
 &= -32 \neq 0
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$$\langle Pat' | e_{male} \rangle = 0$$

$$\langle Pat' | e_{66} \rangle = 0$$

$$\langle Pat' | e_{name} \rangle = 0$$

$$\langle Pat' | e_{sex} \rangle = 0$$

$$\langle Pat' | e_{age} \rangle = 0$$

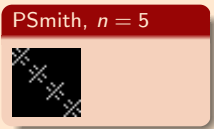
$$\langle Pat' | P_{Smith} \rangle = 0$$

Signatures

Examples

Signatures

Examples



Signatures

Examples

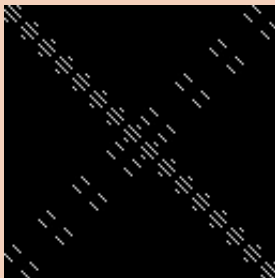
PSmith, $n = 5$



PSmith, $n = 6$



PSmith, $n = 7$



Signatures:



LHS-signature



RHS-signature

Signatures

Dimensions

Signatures

Dimensions

- $2^{\lfloor \frac{n}{2} \rfloor}$ signatures on one of the diagonals.
- Each signature is of dimensions $2^{\lceil \frac{n}{2} \rceil} \times 2^{\lceil \frac{n}{2} \rceil}$.

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Cartan representation

$$b_{2k} = \underbrace{\sigma_1 \otimes \cdots \otimes \sigma_1}_{\text{at least } \lfloor \frac{n}{2} \rfloor} \otimes \sigma_2 \otimes \underbrace{1 \otimes \cdots \otimes 1}_{k-1},$$

$$b_{2k-1} = \underbrace{\sigma_1 \otimes \cdots \otimes \sigma_1}_{\text{at least } \lfloor \frac{n}{2} \rfloor} \otimes \sigma_3 \otimes \underbrace{1 \otimes \cdots \otimes 1}_{k-1}.$$

Recognition tests

Construction

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Vocabulary/Sentence set

Similar sentences, e.g:

- Fido bit Pat.
- Fido bit PSmith.
- Pat fled from Fido.
- PSmith fled from Fido.
- Fido bit PSmith causing PSmith to flee from Fido.
- Fido bit Pat causing Pat to flee from Fido.
- John saw that Fido bit PSmith causing PSmith to flee from Fido.
- John saw that Fido bit Pat causing Pat to flee from Fido.
- etc...

Altogether 42 atomic objects and 19 sentences.

Recognition tests

Agent-Object construction

Works better for:

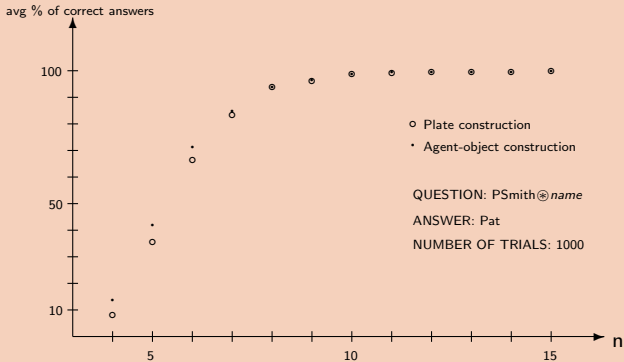
- simple sentences and simple answers

Recognition tests

Agent-Object construction

Works better for:

- simple sentences and simple answers



Recognition tests

Agent-Object construction

Works better for:

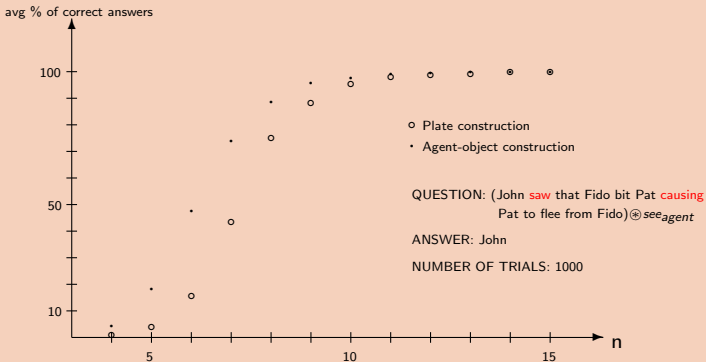
- simple sentences and simple answers,
- nested sentences, from which a rather unique information is to be derived.

Recognition tests

Agent-Object construction

Works better for:

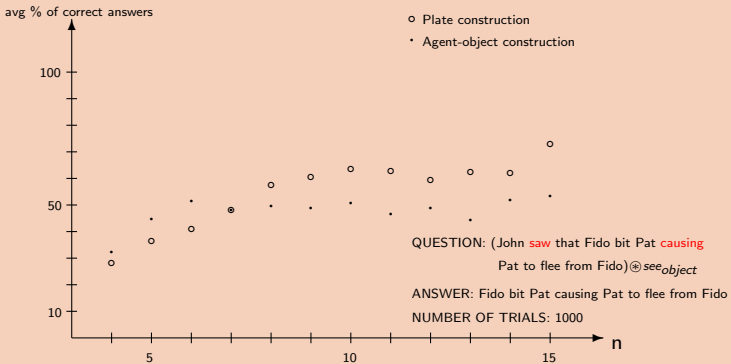
- simple sentences and simple answers,
- nested sentences, from which a rather unique information is to be derived.



Recognition tests

Plate (HRR) construction

Works better for nested sentences, from which a complex information needs to be derived.



Blade linearity

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Problems

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- How often does the system produce identical blades representing atomic objects?

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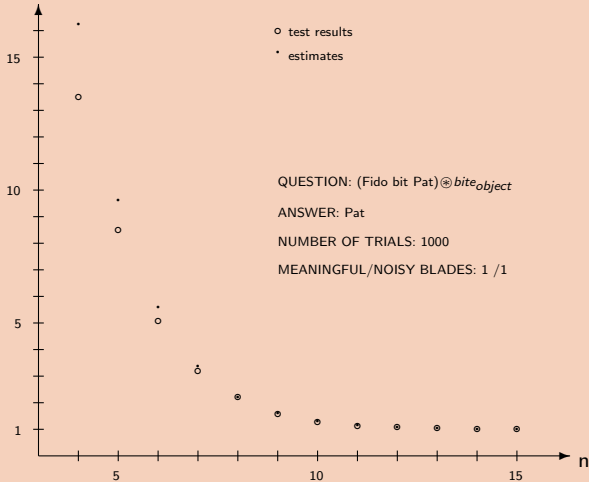
No two chunks of a sentence at any time are identical (up to a constant).

$$\langle A|C \rangle \neq 0 \equiv A \text{ and } C \text{ share a common blade}$$

Blade linearity

One meaningful blade, $L > 0$ noisy blades

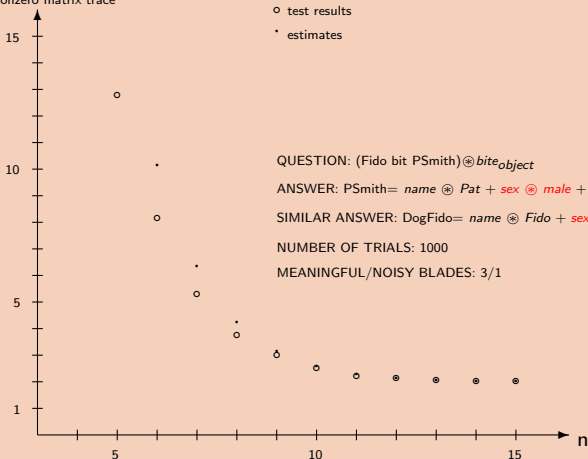
avg number of probings giving
a nonzero matrix trace



Blade linearity

$K > 1$ meaningful blades, $L > 0$ noisy blades

avg number of probings giving
a nonzero matrix trace*



What's next?

Issues

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- Decide on construction (something between Plate and Agent-Object?).

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- Tests for greater n .

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- Decide on construction (something between Plate and Agent-Object?).
- Tests for greater n .
- Scaling.

References

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