Geometric Algebra Approach to Fluid Dynamics

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Outline

- Introduction
- Vector Derivative
- Introduction to Fluid Dynamics
- Proposal of an Extension of the Stream Function
- Conclusion

Introduction

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Introduction

- Many real-world physical problems can be modeled as geometric problems
- Sometimes high-dimensional
- Sometimes requires "exotic" spaces
- Examples: Space-Time, String Theory, Phase Space, ...

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Introduction

- Geometric algebra (GA) encodes information that otherwise has to be extracted laboriously
- GA generalizes well-known concepts
 - to higher dimensions and
 - to spaces of arbitrary metric
- Develop a fluid dynamics calculus based on geometric algebra
- Focus on the stream function

Vector Differentiation

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Vector derivative

$$\nabla = \sum \boldsymbol{e}_{k}(\boldsymbol{e}^{k} \cdot \nabla) = \sum \boldsymbol{e}_{k} \frac{\partial}{\partial x^{k}}$$

- Vector valued
- Properties of differential operator
- Directional derivative $(a \cdot \nabla) = \frac{1}{2}(a \nabla + \nabla a)$
 - Scalar valued
 - Properties of differential operator
 - Grade preserving

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- Special derivatives of vector fields
 - Divergence of **u**(**x**)
 - $\dot{\nabla}_x \cdot \dot{u}(x)$
 - Curl of $\boldsymbol{u}(\boldsymbol{x})$ ("vorticity") $\dot{\nabla}_{\boldsymbol{x}} \wedge \dot{\boldsymbol{u}}(\boldsymbol{x}) = \boldsymbol{\xi}(\boldsymbol{x})$
 - Material Derivative of $\boldsymbol{u}(\boldsymbol{x})$ $\frac{D}{Dt} = (\boldsymbol{u}(\boldsymbol{x},t)\cdot\dot{\nabla}_{\boldsymbol{x}})\dot{\boldsymbol{u}}(\boldsymbol{x},t) + \frac{\partial \boldsymbol{u}(\boldsymbol{x},t)}{\partial t}$

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- A fluid is a mass of moving particles in *n* dimensions
- Initial particle position $x_0 = (x^1, ..., x^n)$
- Particle position at time t $\varphi(\mathbf{x}_0, t) = (\varphi^1(\mathbf{x}_0, t), \dots, \varphi^n(\mathbf{x}_0, t))$
- Velocity vector field describes flow $\frac{\partial \varphi(\mathbf{x_0}, t)}{\partial t} = u(\varphi, t)$
 - Depends on position and time, at which *u* is "measured"

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- Some properties of a flow are purely geometric
 - e.g. Divergence, Curl
- Others follow from physical reality
 - e.g. Existence of Mass Density, Conservation of Mass and Energy, Balance of Momentum, (In-)Compressibility, Viscosity
 - If flows are used as a model for other problems, only subsets of these physical properties may hold

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 Used to calculate flow potential and streamlines



• Usually defined for 2D flows by $u = \nabla \times \psi$, $u = (u_1, u_2, 0)$, $\psi = (0, 0, \psi)$

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 In an *n*-dimensional, incompressible flow there exists a grade *n*-2 function ψ(x, t) with

$$\nabla \wedge \psi = \boldsymbol{u} I_n^{-1}$$

• $0 = \nabla \wedge (\nabla \wedge \psi)$ $= \nabla \wedge (u I_n^{-1})$ $= (\nabla \cdot u) I_n^{-1}$ which only holds exactly with incompressibility condition fulfilled $(\nabla \cdot u) = 0$

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- Ψ is not determined uniquely by that relation; let

 ψ'=ψ+∇∧g, grade(g)=n-3
 u'=(∇∧ψ')I_n
 =∇∧(ψ+∇∧g)I_n
 =u
- To overcome this specify $\nabla \cdot \psi = m$, $\nabla \cdot \psi' = \nabla \cdot (\psi + \nabla \wedge g)$ $= m + \nabla \cdot (\nabla \wedge g) \neq m$

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- Relationship between Ψ and flow field's curl given by $\nabla \wedge u = \nabla \wedge ((\nabla \wedge \psi) I_n)$ $= (\nabla \cdot ((\nabla \wedge \psi) I_n I_n)) I_n^{-1}$ $= (-1)^{\frac{1}{2}n(n-1)} (\nabla \cdot (\nabla \wedge \psi)) I_n^{-1}$
- In 2D this simplifies to the known stream function with

$$\nabla \wedge \boldsymbol{u} = -\nabla^2 \psi I_n^{-1}$$
$$\nabla \cdot \psi = 0$$

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Conclusion

- Fluid dynamics is accessible to GA methods
- GA facilitates algebraic proofs and geometric understanding of fluid dynamics
- GA is suitable to generalize known concepts to arbitrary dimensions and "exotic" spaces

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Thank you for your attention